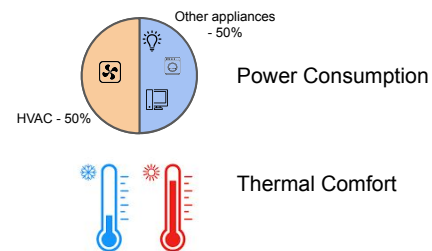


Data Efficient HVAC Control using Gaussian Process-based Reinforcement Learning

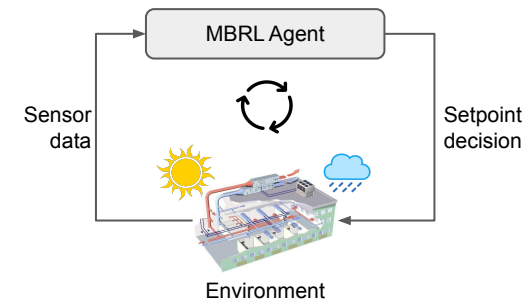
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1. Building HVAC control problem

Dual-objective control with unknown dynamics



Model-based reinforcement learning solutions



2. Challenge and key solution idea

Challenge: biased data distribution; dynamics model fails to generalize with out-of-distribution inputs.

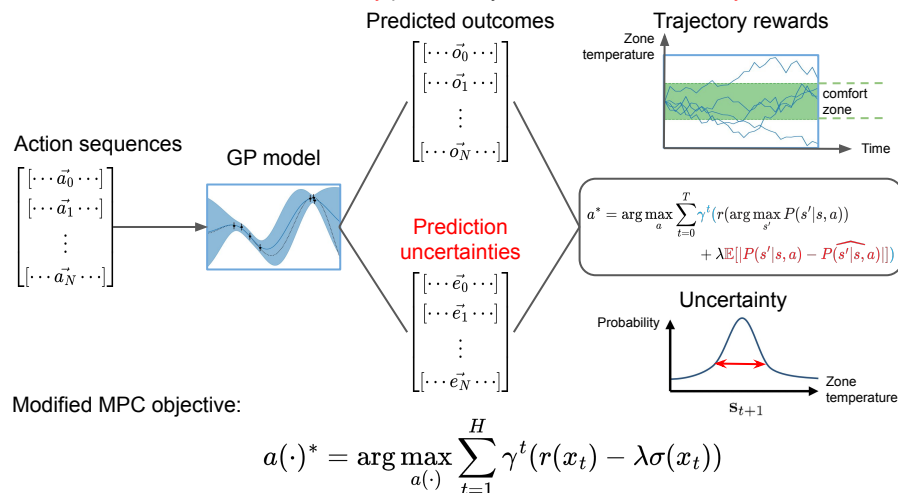
Key idea: instead of try to fit an accurate model, make the controller be **aware** about the **uncertainty**.

Solution: an **epistemic uncertainty-aware control algorithm**.

Uncertainty-aware control algorithm

Gaussian Process + Model Predictive Control

The controller considers the **uncertainty** provided by the **Gaussian Process dynamics model**.



3. Challenge with Gaussian Process Hyperparameters

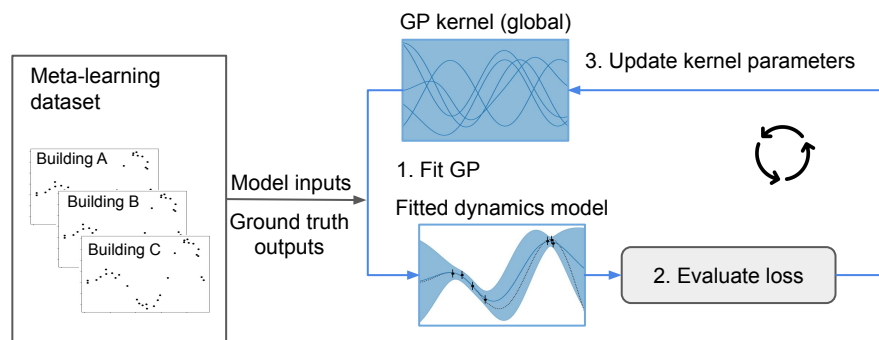
GP performance depends on well-tuned kernel hyperparameters, which is not data-efficient.

RBF kernel: $k(x, x') = \theta_{\text{scale}} \exp\left(-\frac{1}{2}(x - x')^\top \Theta^{-2}(x - x')\right)$ parameter space scales quadratically with feature number.

$\theta_{GP} = \{\theta_{\text{scale}}, \Theta \in \mathbb{R}^{|\mathcal{X}| \times |\mathcal{X}|}\}$, \mathcal{X} : input space

Meta kernel learning

To automatically and effectively set kernel hyperparameters, we use **meta learning** to learn **kernel initialization** from reference building data. This significantly improves data efficiency.



4. Experiment results using EnergyPlus simulations

Training data:

MBRL-SOTA: 1200 days target bldg.

CLUE (ours): 3*300 days reference bldg. + 7 days target bldg.

	Pittsburgh	Tucson	New York	Avg.
Rule-based	.111	.333	.163	.203
MBRL-SOTA	.098	.332	.141	.190
CLUE	.089	.304	.109	.167

12.07% less comfort violation.

Table 1: Comfort violation rate results.

(kWh)	Pittsburgh	Tucson	New York	Avg.
Rule-based	1263.3	467.0	582.9	772.1
MBRL-SOTA	1117.9	388.3	838.5	781.5
CLUE	1134.1	437.5	851.8	807.8

Similar energy savings with the previous SOTA

Table 2: Energy savings results.